21cm X optical correlation & HI clumps with Tianlai low z surveys

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Overview

- Work published in MNRAS 517 (2022) 3, 4637-4655
- Coming soon : low-z observations with Tianlai (~ 1330-1430 MHz)
- Main purpose : "prove the effectiveness of the dense interferometric dish array and transit mode observations of Tianlai"
- two surveys : a mid-latitude band (6 scans around $\delta \sim 50$ deg) and the North Celestial Polar cap (4 scans around or at NCP)
- Forecasts : nearby HI clump (or galaxies) direct detection and cross-correlation with optical wavelength LSS surveys
- 3 parts :
 - Simulation tools, efficiencies
 - Ø direct clumps detection
 - Icross-correlation with optical surveys (SDSS, NCCS)

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Footprints of surveys



Toolbox

- Available in JSkyMap gitlab.in2p3.fr repository (R. Ansari et al.)
- map2vis = visibility simulator : combines sky components + convolution with beam in (l, m) space given array config, frequency
- vis2map = map reconstruction in (l, m) space : noise (photometry, phase) addition 'on the flight' (5mK per sample); pseudo-inverse pointing matrix saved
- filt2map filtering in (l, m) space
- "post processing" : source detection, (cross-) C_l computation (spec_dfreq_ecp module)
- foreground removal methods : local difference or polynom fit (in ν domain)

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Input map (1350 GHz, no noise, NCP)



Reconstructed map (1350 GHz, no noise, NCP)



Power spectra (NCP, 1300-1400 MHz averaged) : filtering



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Power spectra (NCP, 1300-1400 MHz averaged) : foreground subtraction



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Reconstructed maps (1350 MHz, mid-latitude)



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Power spectra (Mid-latitude, 1350 MHz)



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Conclusions

- map reconstruction leaves artefacts (noise + mode mixing)
- NCP case "noise dominated" : reconstruction artefacts lower than noise (thanks to more orientations)
- larger integration time per pixel on NCP ⇒ lower noise per pixel
- midlatitude case covers larger area
- *l* interval selected by fitering and sky coverage
- other conclusions (not shown) :
 - 'polynom' fg subtraction slightly better
 - phase noise can be damaging

Direct clump detection forecast

two step process

- flux threshold determination with simulation
- Use HI mass function (from ALFALFA) to get number of sources vs redshift

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Detection efficiency simulation

- simulate observations with Tianlai 16 dish setup; 5mK noise per visibility sample (3mK could be achieved)
- 4 scans (NCP); 6 scans (43-57 deg.)
- foreground subtraction : simulate observations at 3 freqs (e.g. 1348, 1350 and 1352 MHz), subtract average of outer frequencies
- add sources for central frequency only
- detection algo : DAOStarFinder from photutils python package - several parameters, used mainly threshold (unit = image stddev) to avoid spurious "detections"
- compute detection efficiency vs flux (Jy)

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Detection efficiency towards NCP



efficiency well described by erf function; lower threshold with 3mK noise/sample (orange)

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Detection efficiency at midlatitude



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Number counts

- HI clumps mass function measured by ALFALFA (arXiv :1802.00053) parametrized as Schechter law (parameters seem to vary with position, distance)
- same reference : $\frac{M_{HI}}{M_{\odot}} = 2.356 \times 10^5 D_{Mpc}^2 S_{21}$ S_{21} : integrated HI flux (used ~ 200 km/s velocity dispersion here to get peak flux)
- Flux (Jy) $\Rightarrow M_{HI}(z)$
- integration of the MF above threshold / with efficiency at each z → n(z)
- sum over z → expected numbers of detections per unit area

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Figure 2. The ALFALFA 100 per cent HIMF. The lower panel shows the number counts in logarithmic H i mass bins, and the ...



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Clumps towards NCP



With ~ $100deg^2$: ~ 5 HI clumps at $z \le 0.02$ (~ 12 HI clumps at $z \le 0.03$ for lower noise)

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Clumps - midlatitude case



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- noise is the dominant factor towards NCP : number of clumps would be 2 to 3 times higher with 3mK (~ no impact for mid-lat case)
- HMF parameter variations seen by ALFALFA (near case less favorable?)
- test different observation strategy (e.g. cover larger area towards NCP)?

Cross-correlation with optical surveys

optical surveys :

- midlatitude : SDSS
- NCP : ideal case with rotated SDSS more realistic : estimate incompleteness of NCCS (on going observations with WYIN) wrt SDSS
- estimate HI properties from optical photometry
- cross-correlation significance estimated at maps' power spectra level
 - ▶ midlatitude : C_ℓ cross-spectra
 - ► NCP : smaller area ⇒ flat approximation

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SDSS catalogue

- online queries to 'photo', 'spectro' and 'photo-z' SDSS catalogues
- ~ 900000 objects with δ > 31 deg
- basic information : ID, ra,dec, u,g,r,i,z, type, field, specid, class,redshift,error (can be complemented with other catalogues)
- empiric selection (to avoid "crazy" HI parameters) :
 - galaxy (type=3)
 - .005 < redshift < 1 (avoids e.g. very nearby objects)</p>
 - ► -0.5 < r i < 2.5 ("standard galaxies?")</p>
 - ▶ r i < .8 or redshift > 0.1 ("standard galaxies?")
- ~ 420000 objects

Footprint



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The path to HI flux and parameters

- get the stellar mass from photometry
- Infer the HI mass from stellar mass & photometry
- Scompute the HI integrated flux from HI mass
- ④ get the velocity dispersion from HI mass (⇒ frequency width)
- pass HI flux, frequency (center+width) params list to simulation

- pipelined JSkyMap modules : map2vis , vis2map, filt2map
- Tianlai set-up w/o auto-correlations
- without or with 5 mK noise per visi sample
- maps with all components, HI sources only, foregrounds only, noise only
- planes between 1250 and 1400 MHZ, 1 MHz spacing in 6 'blocks' (data cubes)

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Cross-correlation with input catalog

- build a data cube from input catalog :
 - use only sources' positions (no flux) : normalization of X-correlation arbitrary
 - add a spread in redshift (frequency) according to HI width (gaussian)
 - same frequencies as simulated maps
 - optional shuffling of sources' positions (for cross-checks, error estimation)
- compute the (cross) C_l (harmonic space) of each plane (planes pair) and average them with spec_dfreq_ecp (JSkyMap package)
- foreground subtraction with polynomial fit (or running difference)

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Midlatitude : averaged spectra 1360-1410 MHz



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Midlatitude : summary



NCP spectra (rotated SDSS)

Work with flat sky projection approximation \Rightarrow Fourier spectra



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NCP spectra : incompleteness effect



Outlook

- preparation for Tianlai dish array low-z observations
- 2 foreseen surveys : NCP (7 deg diameter) and midlatitude band, 3-5 mK per pixel noise (2-6 months)
- HI clumps/galaxies direct detection : hard at midlatitude, easier towards NCP (O(10) objects)
- cross-correlation with optical surveys :
 - midlatitude : larger area, very significant signal (several possible methods)
 - NCP : smaller area, on-going optical spectroscopic survey but signal also significant

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Component separation methods



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Midlatitude alternative method (I)

- compute visibilities from catalog data cube \Rightarrow 3D arrays $V_b(RA, desc, \nu)$ for each baseline B
- 1D FFT in ν axis for each baseline and coords
- average cross-power spectra over baselines and coords
- NB : no explicit component separation



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Midlatitude alternative method (II)

- build maps from sources' cube visibilities from method (I) (same params & filtering as in published paper)
- option : subtract average of neighbouring freq. maps
- cross-FFTs in v axis for each pixel + average



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